

ART 34 AMDT

1. Piezoelectric actuator (1) comprising

- a stack of a plurality of individual piezoelectric
5 actuator elements (2, 2', 2''), which are disposed
between inner electrodes (3, 3', 3'') and which contract
or expand in a main oscillation direction (10) in
dependence on an applied electric voltage,

- a first metallization strip (4) and a second
10 metallization strip (5), the inner electrodes (3, 3',
3'') being respectively connected in an alternating
manner to the first or second metallization strip (4)
(5),

- a first outer electrode (6) and a second outer electrode
15 (7) which are respectively fixed to the first or the
second metallization strip (4) (5) in order to
electrically contact the piezoelectric actuator (1) and

- a first connection element (8) and a second connection
20 element (9) for externally contacting the piezoelectric
actuator (1) which are respectively connected to the
first or the second outer electrode (6) (7),

whereby

- the outer electrodes (6) (7) comprise at least one region
which is embodied in such a way that it compensates
25 length variations of the piezoelectric actuator (1) in
the main oscillation direction (10) as a result of its
design and arrangement by means of elastic deformation
exclusively inside a plane which is parallel to the main
oscillation direction (10), and

30 - the outer electrodes (6) (7) have a comb-shaped profile
with contact teeth (11) (11') to contact the
metallization strips (4) (5)

c h a r a c t e r i z e d i n t h a t

8/10

ART 34 AMDT

the outer electrodes (6) (7) have a wave-form conductor plate (16) (16') from which the contact teeth (11) lead away.

2. Piezoelectric actuator (1) according to Claim 1,

5 c h a r a c t e r i z e d i n t h a t
the wave-form conductor plate tapers along its principal axis (18) (18').

3. Piezoelectric actuator (1) according to Claim 1 or 2,

10 c h a r a c t e r i z e d i n t h a t
the contact teeth (11) (11') run parallel to each other and are all the same length at a first end (12) (12') and the contact teeth (11) (11') at this end (12) (12') are soldered to the metallization strips (4) (5) in order to create an
15 electrical contact.

4. Piezoelectric actuator (1) according to one of Claims 1 to 3,

c h a r a c t e r i z e d i n t h a t
20 the outer electrodes (6) (7) are curved at an angle $\alpha < 90^\circ$ in order to be fixed to the piezoelectric actuator (1), parallel to the first, straight end region (12) (12') of the contact teeth (11) (11').

25 5. Piezoelectric actuator (1) according to one of Claims 1 to 4,

c h a r a c t e r i z e d i n t h a t
the outer electrodes (6) (7) on the piezoelectric actuator (1) are fixed mechanically by means of an adhesive (14) to the
30 piezoelectric actuator (1) and the contact teeth (11) (11') are left open when the adhesive (14) is applied for soldering to the metallization strips (4) (5).

6. Piezoelectric actuator (1) according to Claim 5,

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ART 34 ADAPT

1 characterized in that
the adhesive (14) is designed and arranged in such a way that
electric insulation is ensured between the outer electrodes
(6) (7) on the one hand and the piezoelectric actuator
5 elements (2, 2', 2'') and the inner electrodes (3, 3', 3'') on
the other hand.

7. Piezoelectric actuator (1) according to Claim 5 or 6,
c h a r a c t e r i z e d i n t h a t
10 the thickness of the layer of adhesive (14) between the outer
electrodes (6) (7) on the one hand and the piezoelectric
actuator elements (2, 2', 2'') and the inner electrodes (3,
3', 3'') on the other hand is determined by the admixture of
particles of a preset size.

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8. Piezoelectric actuator (1) according to one of Claims 5 to
7,
c h a r a c t e r i z e d i n t h a t
the adhesive (14) is fuel-resistant.

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9. Piezoelectric actuator (1) according to one of the
preceding claims,
c h a r a c t e r i z e d i n t h a t
the piezoelectric actuator (1) is completely covered with
25 adhesive (14).

10. Piezoelectric actuator (1) according to one of the
preceding claims,
c h a r a c t e r i z e d i n t h a t
30 the outer electrodes (6) (7) are made from a bronze alloy
using etching.